

ConnectedFactories Webinar

Standards for digital manufacturing

20 October 2020
at 09:30

ISO 10303 in EU Projects like Kyklos 4.0,
Arrowhead Tools, Change2Twin

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CONNECTED
FACTORIES



Digital Twin for every manufacturing SME!

Change2Twin is a European project which supports manufacturing SMEs in their digitalization process by providing Digital Twin solutions. The concept of Digital Twin is one of the big game-changers in manufacturing and allows companies to significantly increase their global competitiveness.

- 18 Partners, Grant Agreement nr. 951956
- Web: <https://www.change2twin.eu/>



- Digital Innovation Hubs
- Part of I4MS: the EU initiative to digitalise the manufacturing industry

Packaging Industry



Process Manufacturing



Additive Manufacturing



Biomedical Manufacturing



Change2Twin

Economic Impact

- Reduce new product time-to-market and lead time
- Reduce operational costs
- Improve overall quality
- Improve efficiency of service

Social Impact

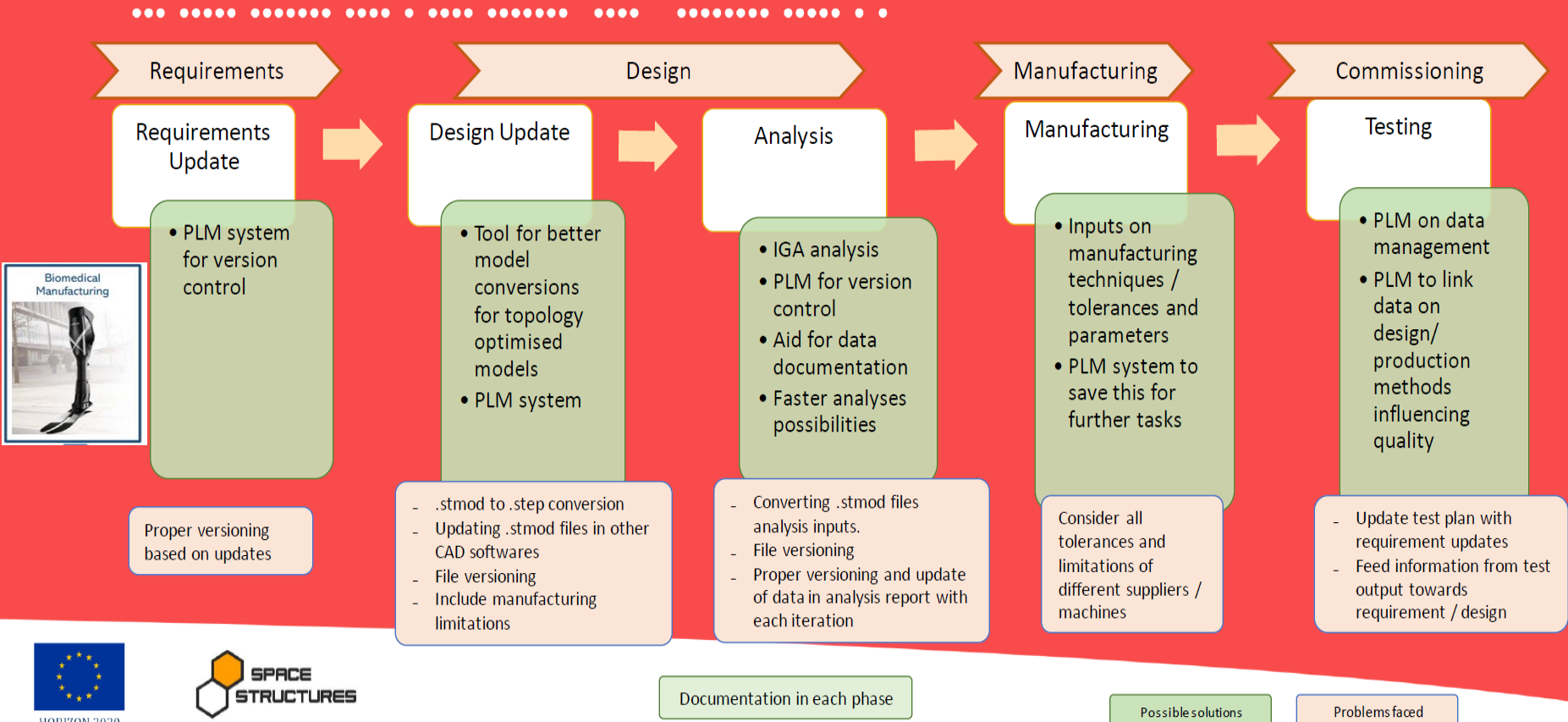
- Create high-skilled jobs
- Improve working conditions
- Create novel resource management strategies

Environmental Impact

- Reduce waste
- Lower energy consumption
- Reduce material consumption



Prosthesis Adapter: Considered Solutions



Jotne provides Digital Twins capabilities to overcome existing issues SMEs are facing

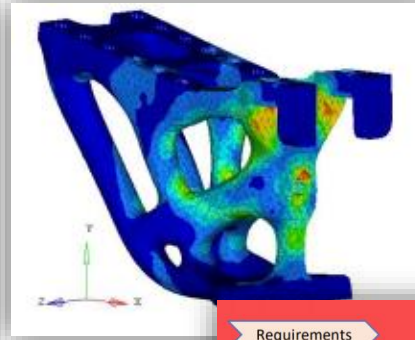
Data Storage
– Collect data along the life of a product or project cycle

Interoperability

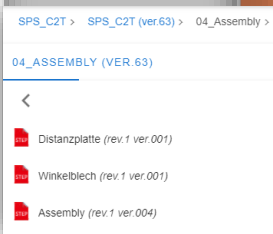
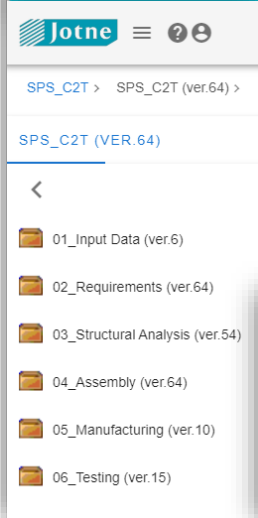
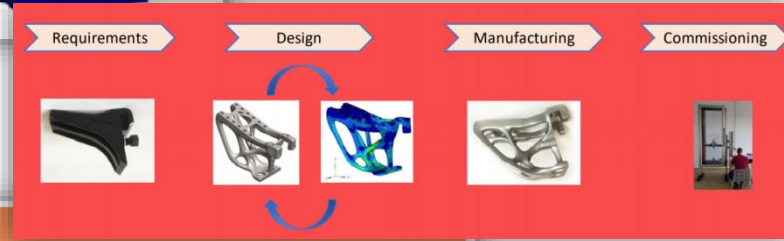


Data Exchange -
Export/import facilities using ISO 10303-239/209

Data Archiving -
project data can be exported in a standard format that does not depend on specific software



Unified ISO 10303 Repository



SPS working on Pilot Use Case - Prosthesis Adapter in collaboration with Jotne

Integration of other CAD tool with PLM

CAD and document management

Change management Functionality

Follow Standardised procedure for data exchange

CHANGE2TWIN funding scheme

- **€10.000 Assessment Voucher:** get a ready to use twinning recipe
- **€90.000 Deployment Voucher:** get the digital twin based on the recipe and test it
- **2x2 Open Calls** for SMEs: 2021 and 2023
- **multistakeholder principle:** manufacturing SMEs, technology providers, Digital Innovation Hubs



KYKLOS 4.0 Factsheet



KYKLOS 4.0

KYKLOS 4.0	An Advanced Circular and Agile Manufacturing Ecosystem based on rapid reconfigurable manufacturing process and individualized consumer preferences
Project Number	872570
Starting Date	01/01/2020
Project Duration	48 months
Call (part) Identifier	H2020-DT-2019-1
Topic	Digital Manufacturing Platforms for Connected Smart Factories
Budget	€19.227.110
Number of partners	29
Coordinator	Technalia - Jason.Mansell@tecnalia.com
Web site	https://kyklos40project.eu/



Rationale

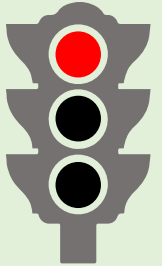


KYKLOS 4.0

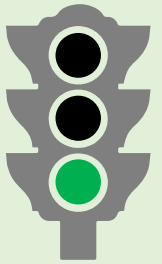


Manufacturing companies **consume** high amounts of energy as well as **natural resources** in their product-making processes:

- The respective amounts and overall costs of product making are increasing
- EU energy prizes are continuously increasing
- Raw materials price trend is ascending, increasing short term volatility



Optimizing the manufacturing processes becomes “a must” to ensure **sustainability**



KYKLOS 4.0 Technology & Solutions

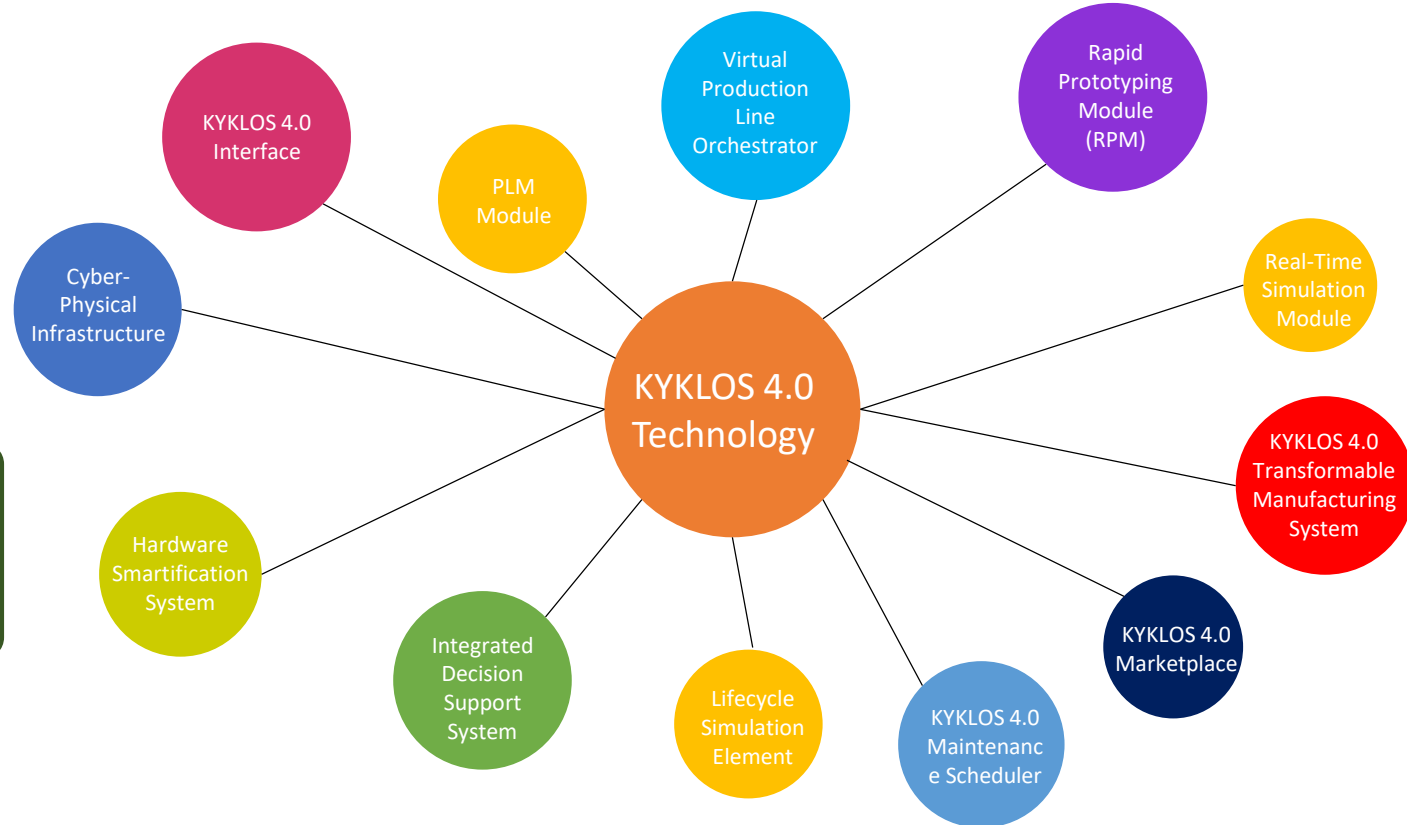


KYKLOS 4.0

KYKLOS 4.0 technology involves a set of **intelligent tools for real-time analytics & prediction, and recommendation systems**, integrated into the KYKLOS 4.0 configuration environment

Rapid Reconfigurable Manufacturing Process

Individualization of Consumer Preferences



KYKLOS 4.0 Pilots



KYKLOS 4.0

KYKLOS 4.0 will **demonstrate** the transformative effects that Circular Production System (CPS), Product Life Management (PLM), Life Cycle Analysis (LCA), Augmented Reality (AR) and Artificial Intelligence (AI) technologies and methodologies will have to the **Circular Manufacturing** framework

Large-scale piloting in 7 pilots to demonstrate the technical, environmental and economic viability of KYKLOS 4.0 Ecosystem

Pilots will be divided into two main categories: Pilots related to **Smart Manufacturing**, and to **Circular Manufacturing** (energy efficiency and waste management) framework

Smart Manufacturing Pilots

01 Aerospace Pilot
(GENERAL ELECTRIC and KANFIT3D facilities – Israel)

02 Electronic Devices/Equipment Pilot
(VESTEL facilities – Turkey)

03 Medical Pilot
(PRO MEDICARE facilities – Italy)

04 Electronic Manufacturer Pilot
(CONTINENTAL facilities – Romania)

Circular Manufacturing Pilots

01 Automotive Pilot
(DIGRO facilities – Italy)

02 Shipyard Pilot
(ASTANDER facilities – Spain)

03 Food Industry Pilot
(PINDOS Cooperative facilities – Greece)



VESTEL

Continental

ASTANDER



COOP GROUP




The KYKLOS 4.0 project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 872570. This document reflects only authors' views. The EC is not liable for any use that may be done of the information contained therein

KYKLOS 4.0 Open Calls



KYKLOS 4.0



KYKLOS 4.0 will organize two Open Calls during the project with the objective of **engaging European SMEs** in the design and implementation of highly innovative experiments/prototypes using research infrastructure available within the framework of the project

Several events, including online webinars and local face-to-face events across Europe are expected to be implemented within the framework of the two Open Calls

Funding will be provided to projects led by small consortia (third parties) and targeting **innovative concepts**. Each project is expected to define their own project objectives while adhering to the larger objectives and vision of the KYKLOS4.0 project

A total of **€3M** has been budgeted for the KYKLOS 4.0 Open Calls. In principle, €1M for the 1st and €2M for the 2nd Open Call. **Awarded projects may receive up to €150.000**, with each third party receiving a maximum of €60.000



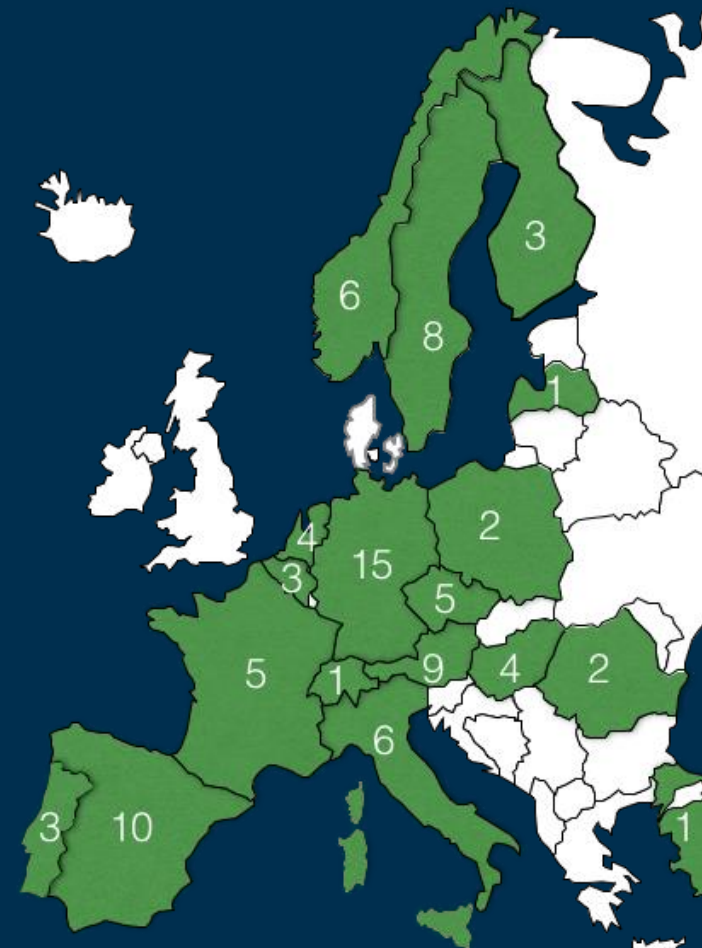
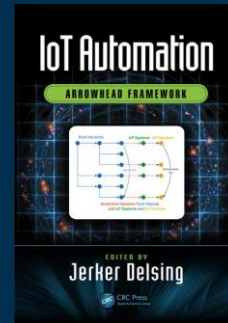
Arrowhead Tools

Europe's largest Automation and Digitalisation Engineering project

- Joint European effort in 18 countries
- 80 partners
- 90 M€ budget
- Duration 2019-2022

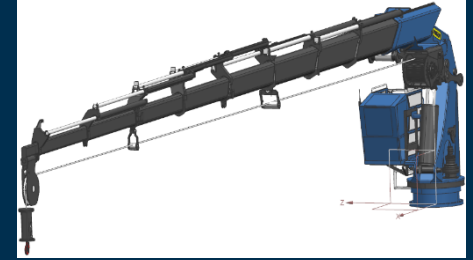
Coordinator: Prof. Jerker Delsing,
Lulea University of Technology

<https://www.arrowhead.eu/>

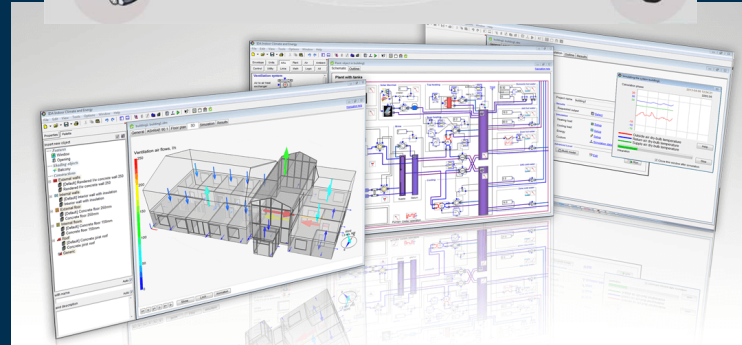


Engineering efficiency improvements

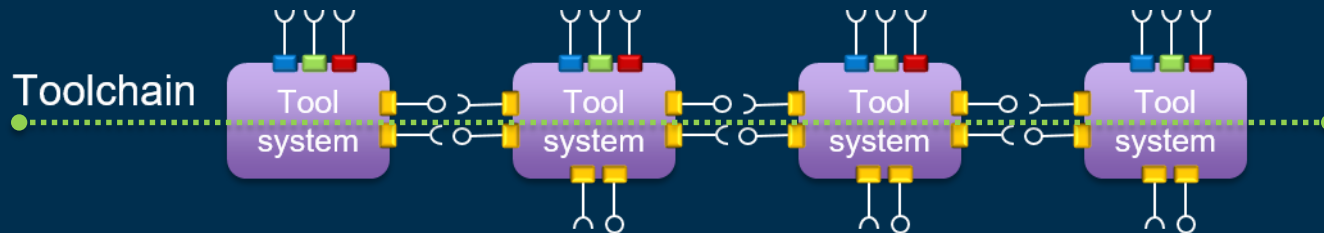
Validation and verification in 21 advanced use cases



- Automotive
- Mining
- Electronics



- Software
- Building Sector
- Offshore



OBJECTIVES & FOCUS AREAS

#1 Reduction of solutions engineering costs

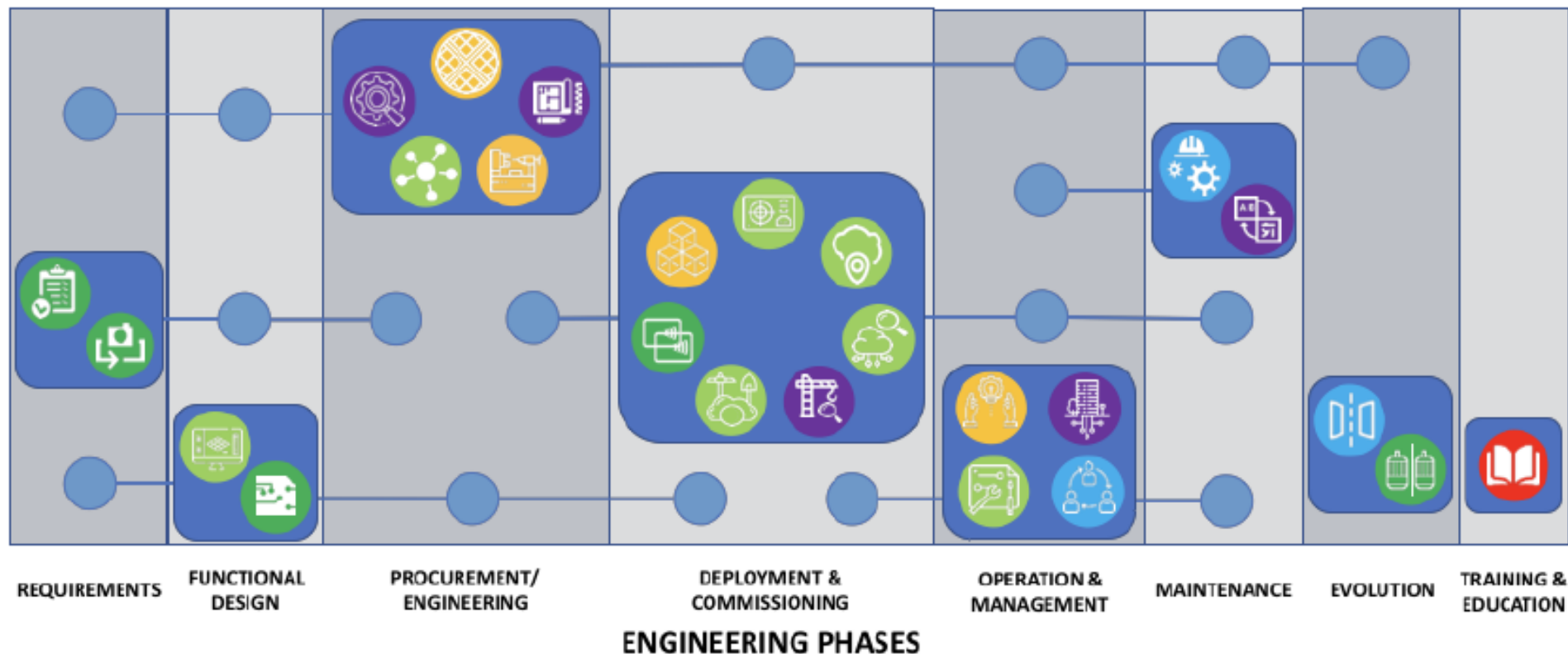
#2 Interoperability for IoT and SoS engineering tools

#3 Interoperability and integration of data from legacy automation engineering tools to the Arrowhead Framework integration platform

#4 Integration platform interoperability with emerging digitalisation and automation framework

#5 Flexible, interoperable and man- ageable security for digitalisa- tion and automation solutions

#6 Training material for professional engineers



A comparison of IoT-SoS Architectures & Platforms

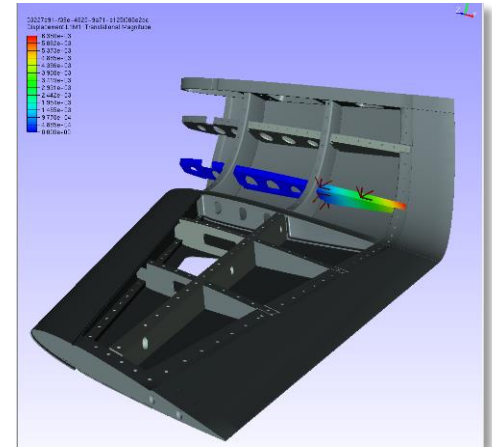
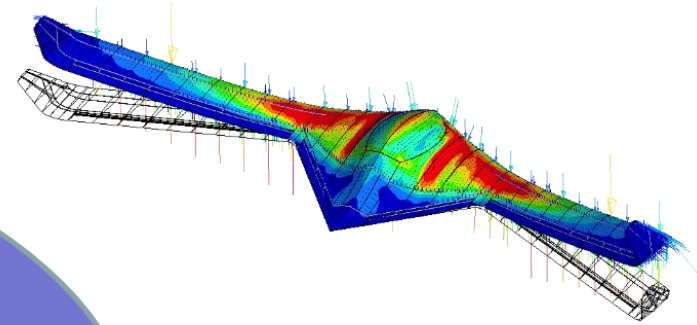
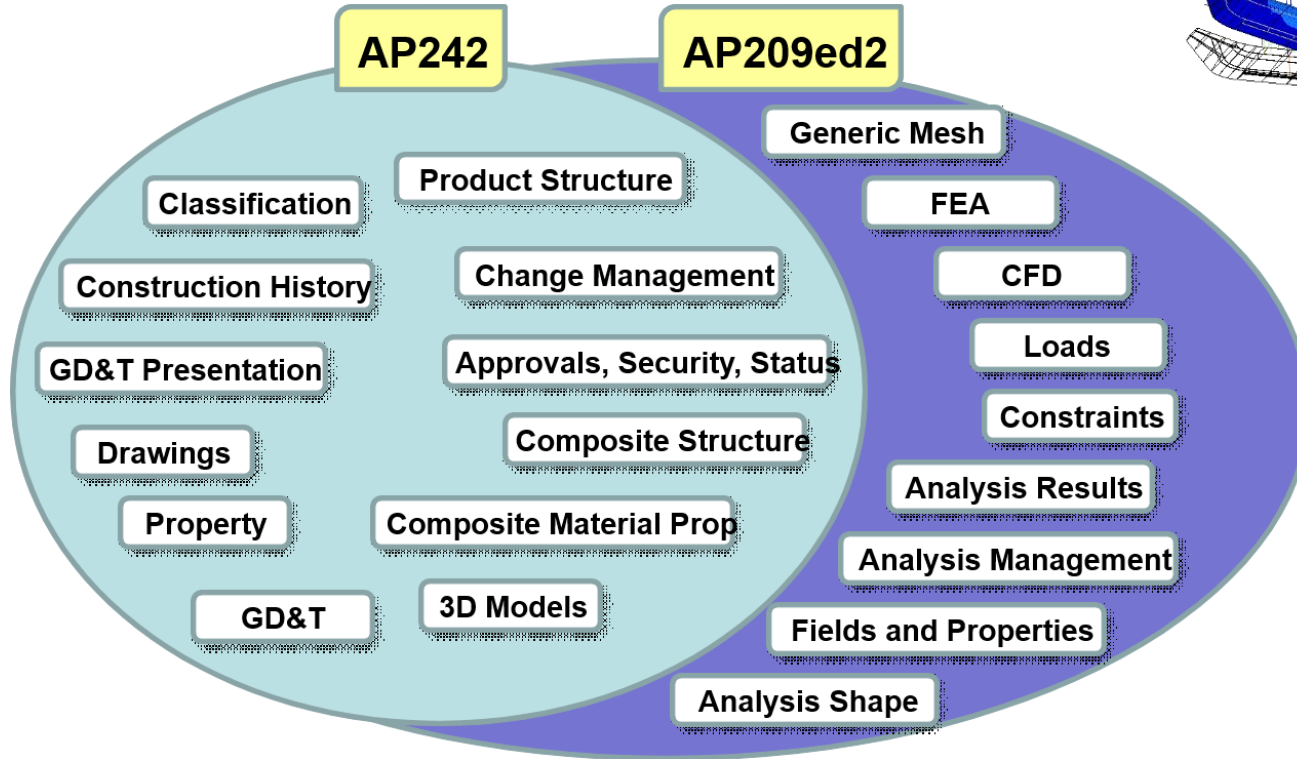
Features	Arrowhead	AUTOSAR	BaSyx	FIWARE	IoTivity	LWM2M	OCF
Key principles	SOA, Local Automation Clouds	Runtime, Electronic Control Unit (ECU)	Variability of production processes	Context awareness	Device-to-device communication	M2M, Constrained networks	Resource Oriented REST, Certification
Real-time	Yes	Yes	No	No	Yes (IoTivityConstrained)	No	No
Run-time	Dynamic orchestration and authorization, monitoring, and dynamic automation	Runtime Environment layer (RTE)	Runtime environment	Monitoring, dynamic service selection and verification	No	No	No
Distribution	Distributed	Centralize	Centralize	Centralize	Centralize	Centralize	Centralize
Open Source	Yes	No	Yes	Yes	Yes	Yes	No
Resource accessibility	High	Low	Very low	High	Medium	Medium	Low
Supporters	Arrowhead	AUTOSAR	Basys 4.0	FIWARE Foundation	Open Connectivity Foundation	OMA SpecWorks	Open Connectivity Foundation
Message patterns	Req/Repl, Pub/sub	Req/Repl, Pub/sub	Req/Repl,	Req/Repl, Pub/sub	Req/Repl, Pub/sub	Req/Repl	Req/Repl
Transport protocols	TCP, UDP, DTLS/TLS	TCP, UDP, TLS	TCP	TCP, UDP, DTLS/TLS	TCP, UDP, DTLS/TLS	TCP, UDP, DTLS/TLS, SMS	TCP, UDP, DTLS/TLS, BLE
Communication protocols	HTTP, CoAP, MQTT, OPC-UA	HTTP	HTTP, OPC-UA	HTTP, RTPS	HTTP, CoAP	CoAP	HTTP, CoAP
3rd party and Legacy systems adaptability	Yes	Yes	Yes	Yes	No	No	No
Security Manager	Authentication, Authorization and Accounting Core System	Crypto Service Manager, Secure Onboard Communication	--	Identity Manager Enabler	Secure Resource Manager	OSCORE	Secure Resource Manager
Standardization	Use of existing standards	AUTOSAR standards	Use of existing standards	FIWARE NGSI	OCF standards	Use of existing standards	OCF standards

C. Paniagua and J. Delsing, "Industrial Frameworks for Internet of Things: A Survey," in *IEEE Systems Journal*, doi: 10.1109/JSYST.2020.2993323.

www.arrowhead.eu/arrowheadframework and download www.github.com/arrowhead-f

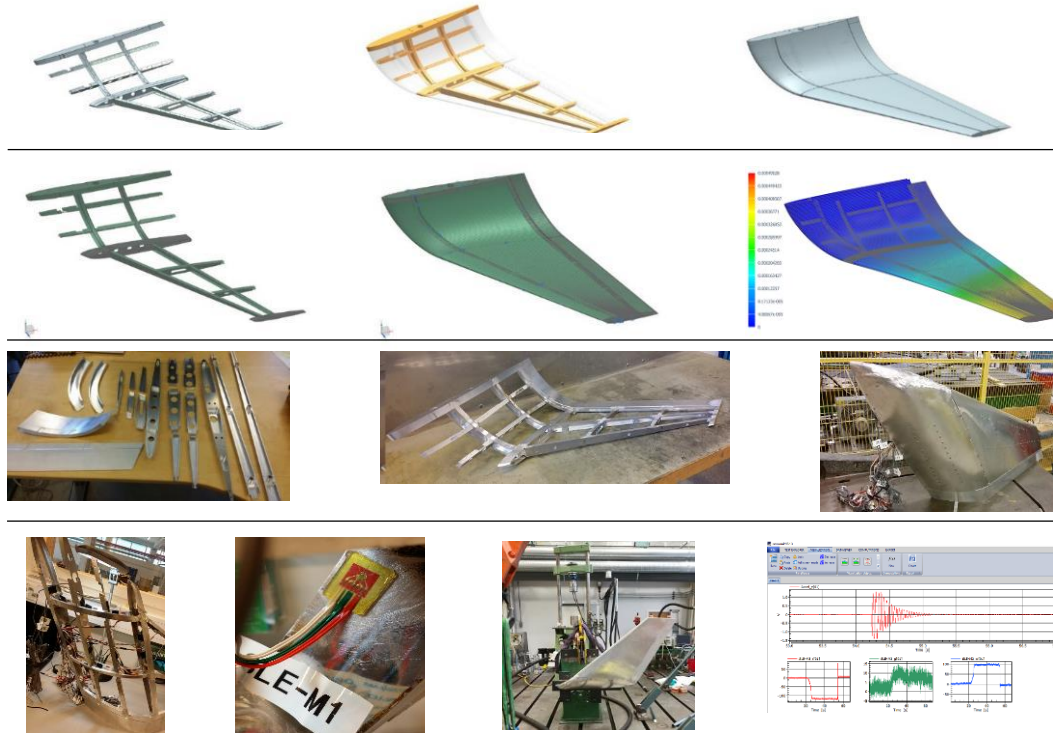
Norwegian Use Case: Digital twins and structural monitoring





Using AP209 for Simulation and structural test data

Some related SW



Design CAD

Analysis FEM

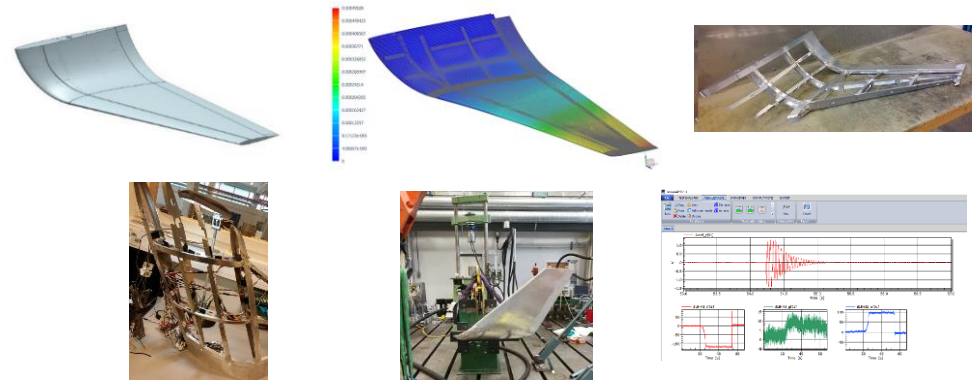
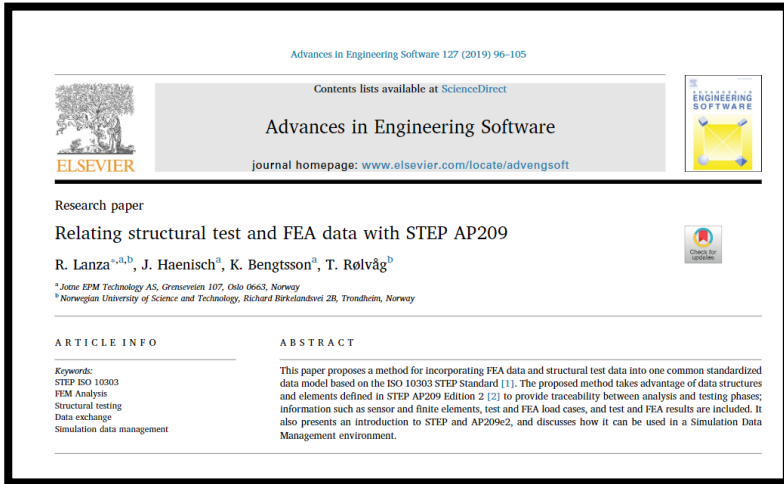
Manufacturing

Sensor data



- Part of PhD study:
 - Investigate the use of AP209 to handle Structural test data and it's relations to Simulation data.
 - Paper in *Advances in Engineering Software*:
<https://www.sciencedirect.com/science/article/pii/S0965997818301947>

PhD and project with Lockheed Martin (Crystal Project):
 Winglet prototype design by Lockheed Martin
 Produced at NTNU
 Analyzed (FEA)
 Mounted sensors and set in test rig
 FEA load cases tested physically
 Design (CAD) → AP209
 Simulation data → AP209
 Structural Test data → AP209
 All data managed in AP209 in Jotne's SDM tool (EDMopenSimDM)
 All traceability kept

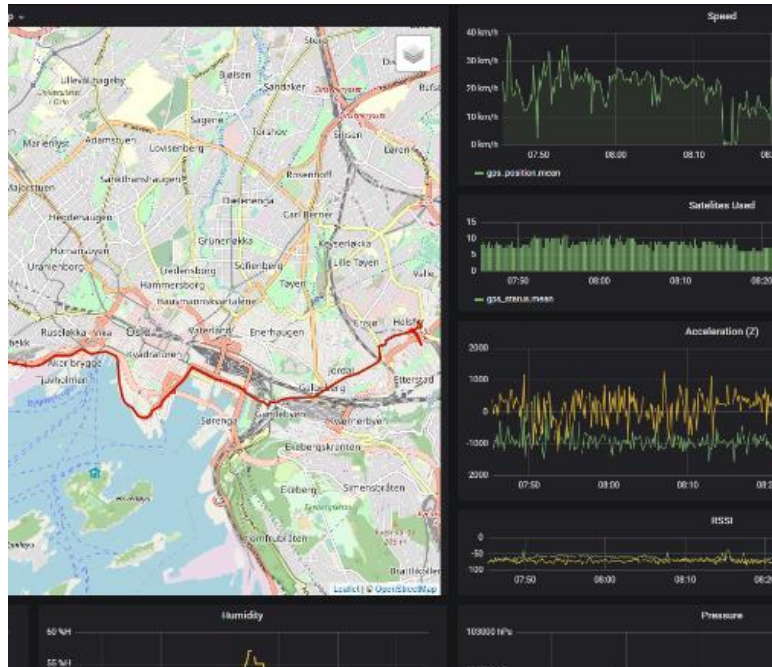


The Challenge

Sensor data in the cloud



Sensor data in the ISO 10303 cloud PLM repository



- ▼ D00 / ASD/AIA Bike
- ▶ DA0 / Wheels
- ▶ DA1 / Brake System
- ▶ DA2 / Steering System
- ▼ DA3 / Frame System
 - DA3-10 / Main Frame
 - DA3-20 / Saddle
 - Tellu-sensor

Representation of the aggregate property

time	ax (m/s ²)	ay (m/s ²)	az (m/s ²)	battery (mV)	humidity (RH)	pressure (Pa)	roll (dB)	temperature (C)
2.7.2010, 09:16:46	176	-100	-989	3223	30	99581	-77	22.77
2.7.2010, 09:16:56	-1	5	-1028	3217	30	99582	-71	22.76
2.7.2010, 09:17:02	241	-142	-1061	3217	30	99581	-73	22.75
2.7.2010, 09:17:17	-167	77	-1010	3223	30	99582	-57	22.74
2.7.2010, 09:17:27	-209	86	-1000	3217	30	99581	-48	22.73
2.7.2010, 09:17:37	-207	83	-1001	3223	30	99583	-48	22.73
2.7.2010, 09:17:47	-204	84	-1000	3217	30	99582	-57	22.73
2.7.2010, 09:17:57	-205	82	-998	3223	31	99582	-58	22.72
2.7.2010, 09:18:07	-209	82	-1006	3223	31	99582	-57	22.72
2.7.2010, 09:18:17	-203	81	-1001	3217	31	99582	-44	22.72
2.7.2010, 09:18:27	80	-3	-1004	3217	31	99582	-65	22.72
2.7.2010, 09:18:37	-10	14	-1002	3223	31	99583	-63	22.72
2.7.2010, 09:18:47	65	-34	-1027	3223	31	99585	-66	22.72
2.7.2010, 09:18:57	87	-12	-997	3217	31	99582	-58	22.71
2.7.2010, 09:19:07	-101	45	-1019	3223	31	99583	-58	22.71
2.7.2010, 09:19:17	-118	50	-1014	3223	31	99583	-48	22.71
2.7.2010, 09:19:27	-110	48	-1017	3223	31	99583	-50	22.71
2.7.2010, 09:19:37	-114	51	-1013	3217	31	99582	-45	22.71
2.7.2010, 09:19:47	-109	46	-1013	3223	31	99580	-48	22.72
2.7.2010, 09:19:57	-116	45	-1018	3217	31	99581	-58	22.72
2.7.2010, 09:20:07	116	-101	-1072	3223	31	99579	-44	22.71
2.7.2010, 09:20:17	304	-140	-981	3223	31	99579	-40	22.71
2.7.2010, 09:20:27	151	-101	-1029	3211	31	99582	-44	22.71
2.7.2010, 09:20:38	182	-60	-1006	3223	31	99584	-41	22.71
2.7.2010, 09:20:48	159	-47	-1007	3217	31	99585	-43	22.71
2.7.2010, 09:20:58	145	-14	-1011	3217	31	99584	-41	22.71
2.7.2010, 09:21:08	183	-72	-943	3223	31	99584	-41	22.71
2.7.2010, 09:21:18	68	-166	-1105	3223	31	99584	-41	22.7
2.7.2010, 09:21:28	164	-4	-771	3217	31	99585	-42	22.7
2.7.2010, 09:21:40	249	-99	-1008	3223	31	99585	-42	22.7



SENSORS



GATEWAY



TELLUCLLOUD



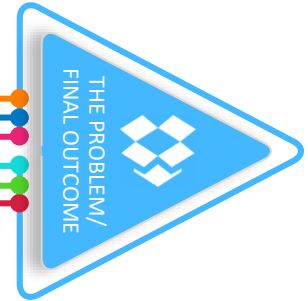
AH FRAMEWORK



REST SERVICES



PLM STANDARDS



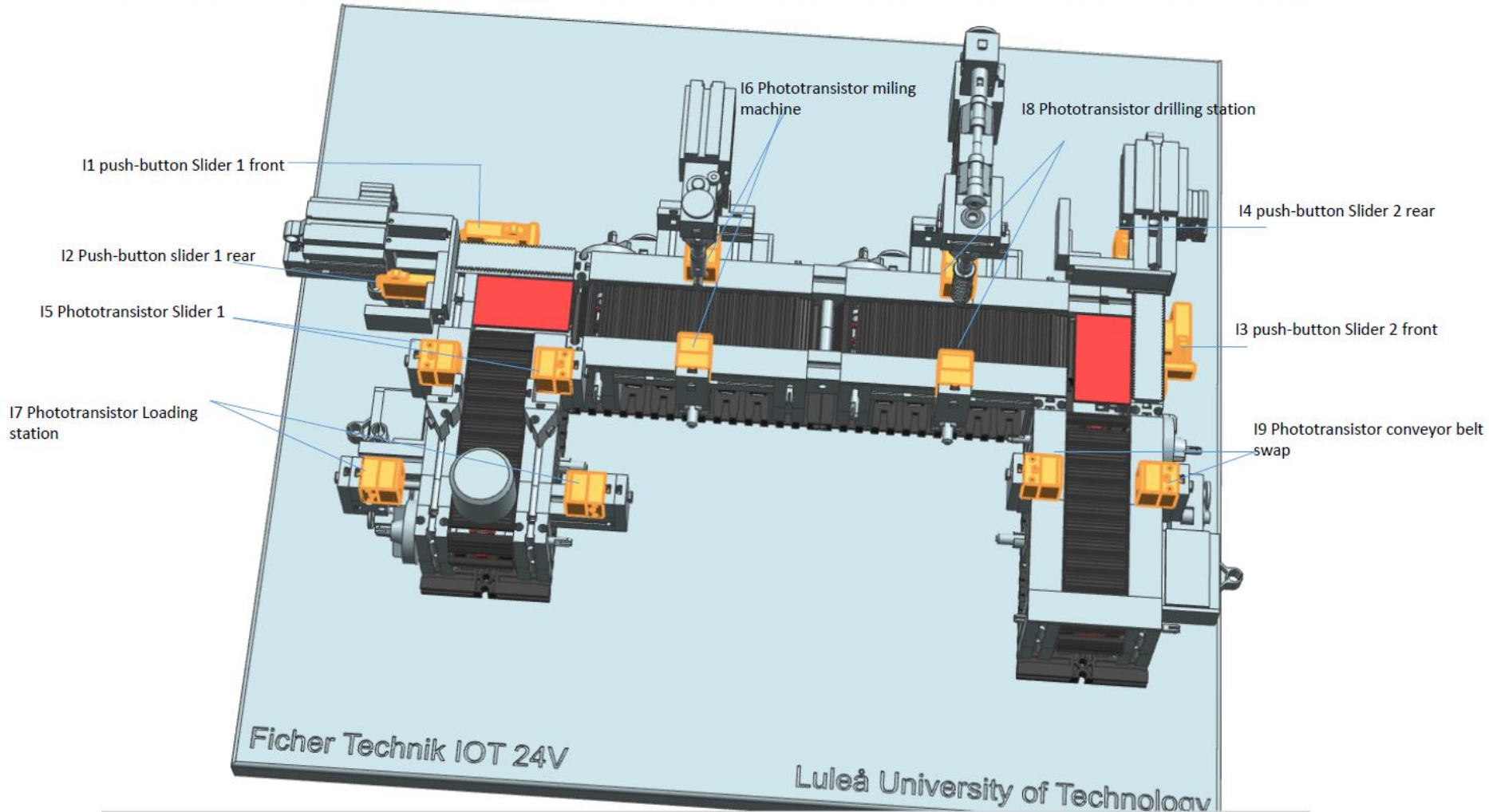
- Read: GET
- Read: GET
- Create: POST
- Update: PUT
- Delete: DELETE

- ▼ D00 / ASDIAIA Bike
 - ▶ DA0 / Wheels
 - ▶ DA1 / Brake System
 - ▶ DA2 / Steering System
 - ▼ DA3 / Frame System
 - DA3-10 / Main Frame
 - ▶ Tellu-sensor

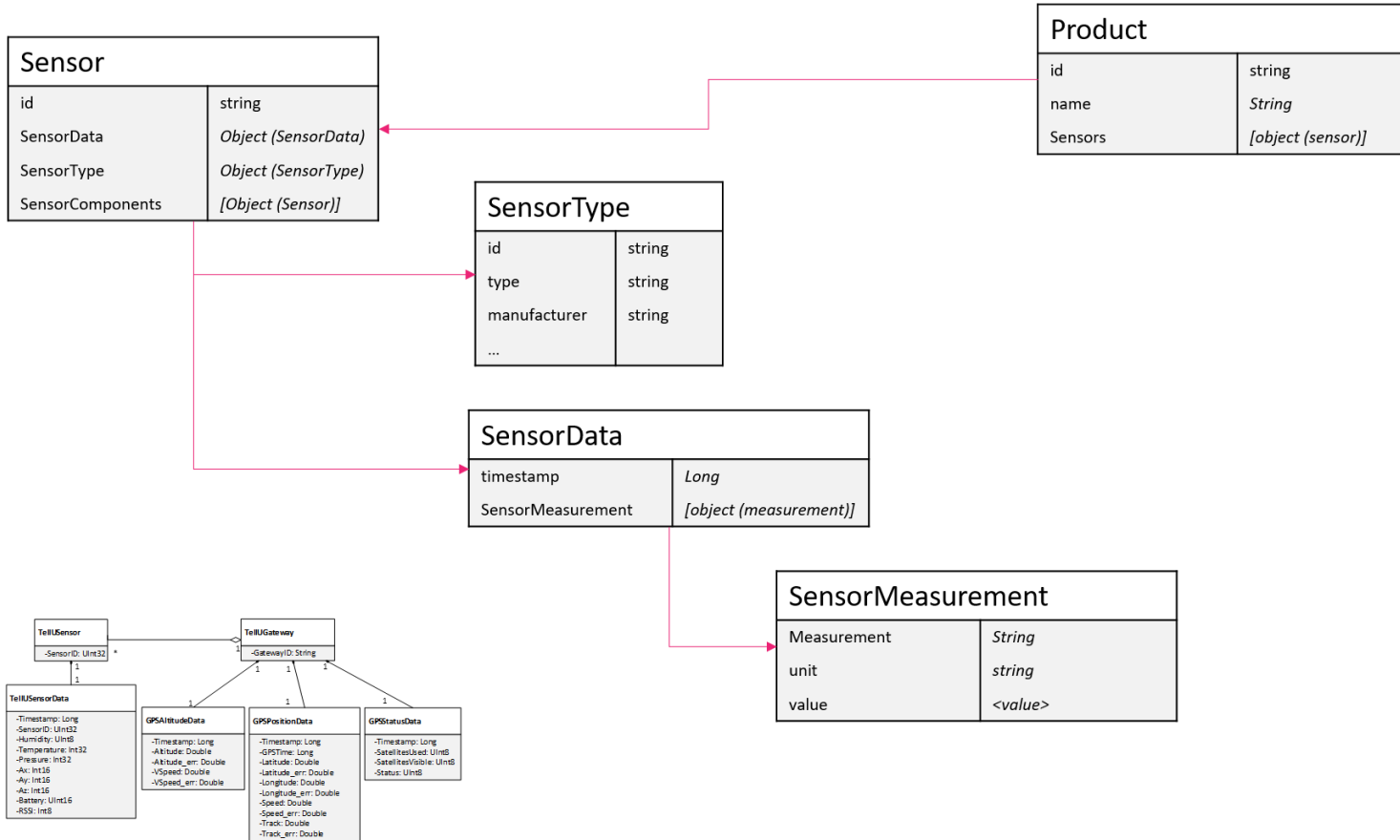


ISO 10303-242, implemented to the repository and also demonstrated for the Fischer Factory

AssemblyFicherTechnik OPCUA_v2.prt



First we needed create the sensor data model (1)



What we did (2) – AHT Producer, Consumer

- Configured and run the following AHT components:

–Service registry

Service Registry

–Authentication

Authorization

–Orchestration

Orchestration

–Gatekeeper

GateKeeper

–Message broker(ActiveMQ)



What we did (3)

- Created the services to connect sensor data to the ISO 10303 repository.
 - <https://trueplm.i-spb.com/EDMtruePLM/swagger.html>

true-plm-provider-controller True PLM Provider Controller

GET	/sensor/{proj}	getSensorsInfoService
GET	/sensor/{proj}/{sn}	getSensorInfoService
GET	/sensor/{proj}/{sn}/{prop}	getSensorDataService
POST	/sensor/{proj}/{sn}/{prop}	addSensorDataService



Digital Twin Based Crane Monitoring

Digital Twin: As simulated



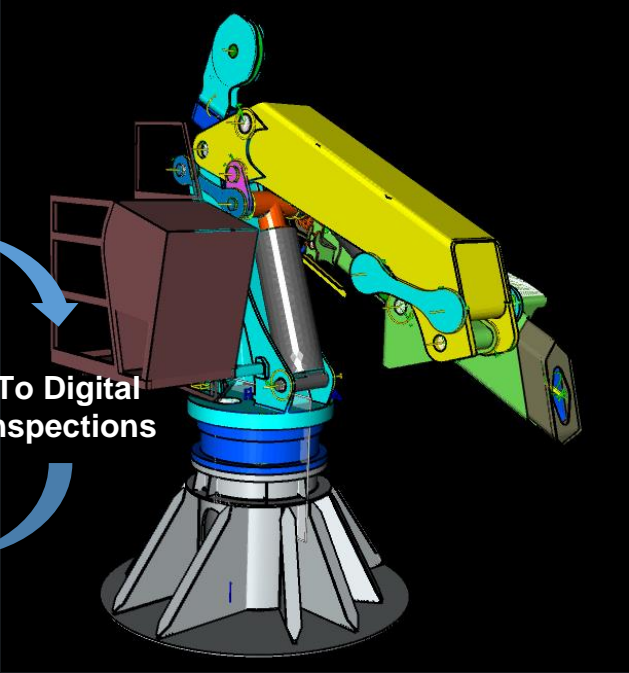
In Operation



Crane Implementation



From Physical
Inspections



To Digital
Inspections



Digital Twin FEA technology

Our Digital Twin models are simulated real time in FEDEM:



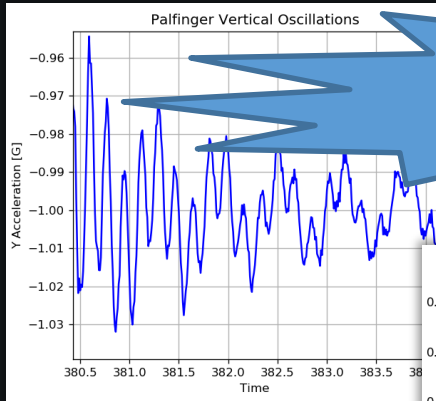
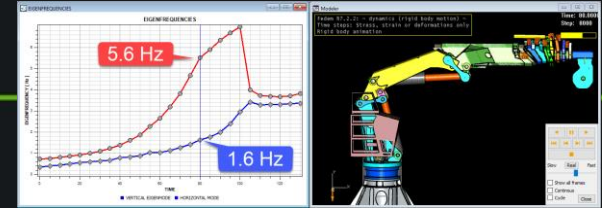
Mesh too dense
to be shown
(3.6 mill DOFs)

- CAE
 - 3D modelling / idealization
 - Joint / spring / damper / sensor modelling
 - Substructuring (25 super elements)
 - Meshing
- Dynamic simulation (nonlinear FEA)
 - Forces, Positions, Velocities and Accelerations
- Structural Analysis
 - Stresses / strains
 - Vibration frequencies
 - Damage / durability
- Control / hydraulics
 - PI / PD / PID Controllers
 - Closed loop dynamics

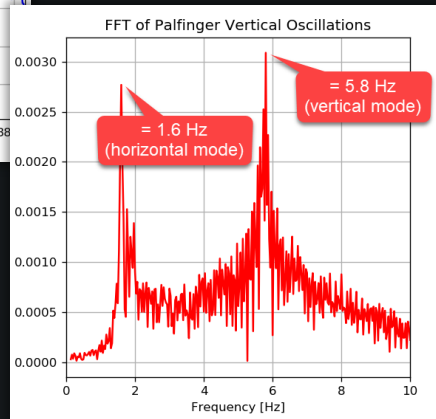
$$M(\mathbf{r}, \dot{\mathbf{r}}) \ddot{\mathbf{r}}(t) + C(\mathbf{r}, \dot{\mathbf{r}}, \ddot{\mathbf{r}}) \dot{\mathbf{r}}(t) + K(\mathbf{r}, \mathbf{t}, \sigma) \mathbf{r}(t) = \mathbf{F}(t)$$
$$\boldsymbol{\varepsilon}_{\text{rosette}} = [\mathbf{T}_r \tilde{\mathbf{B}} \mathbf{T} \mathbf{A} \mathbf{L} \mathbf{H}] \mathbf{v}_{\text{sup}}$$

Palfinger DT Validation

Measured eigenfrequency at minimum extension:



Perfect match mode 1 (1.6 Hz)
Close match mode 2 (5.8 versus 5.6 Hz)



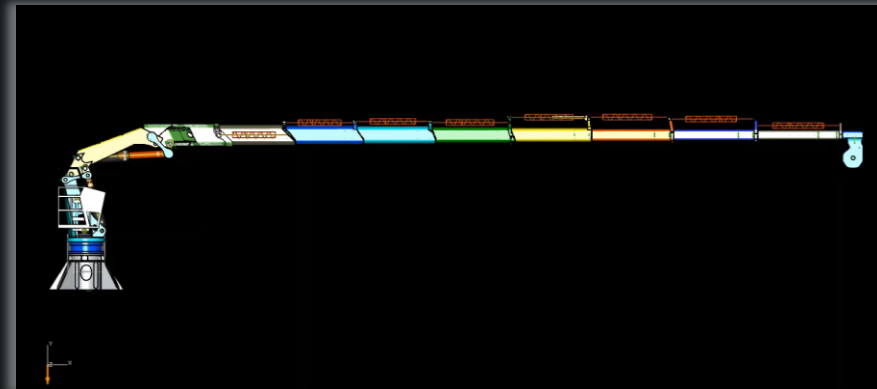
Palfinger DT Validation

FEDEM runs faster than
real time with 3.6 mill
DOFs!

Crane deployment takes 130 seconds:



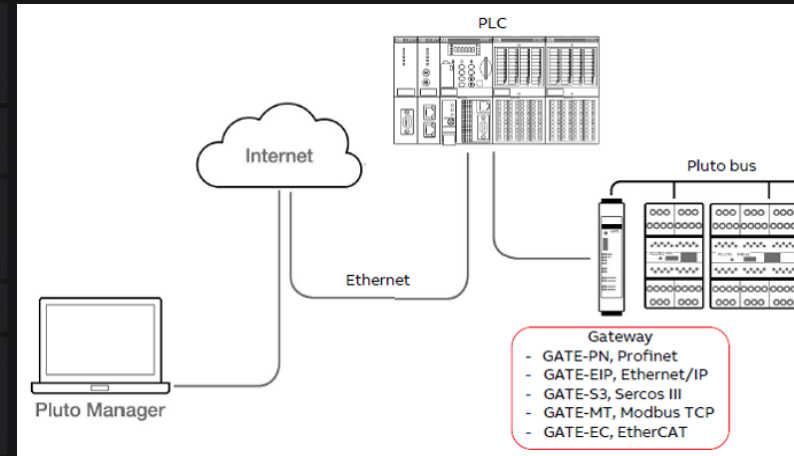
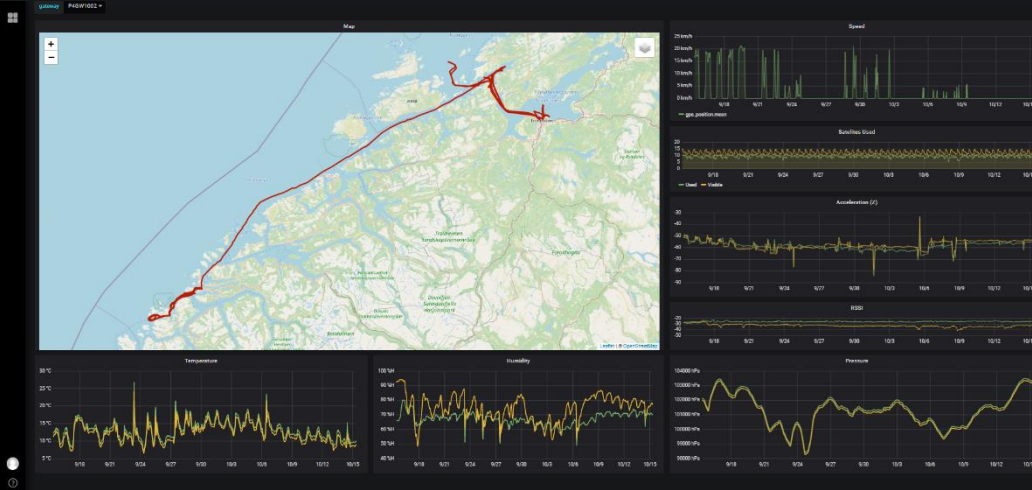
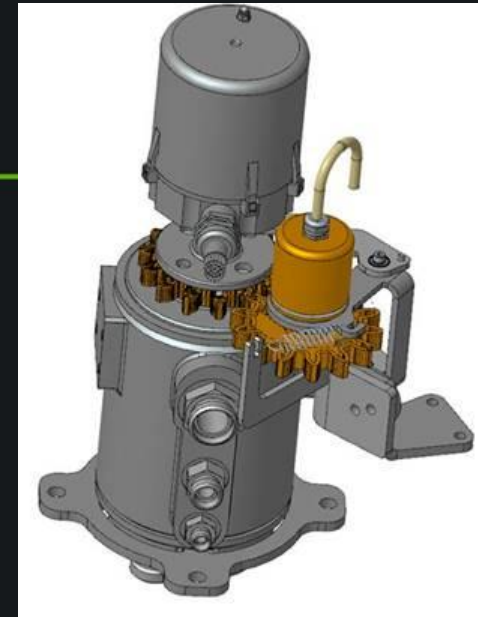
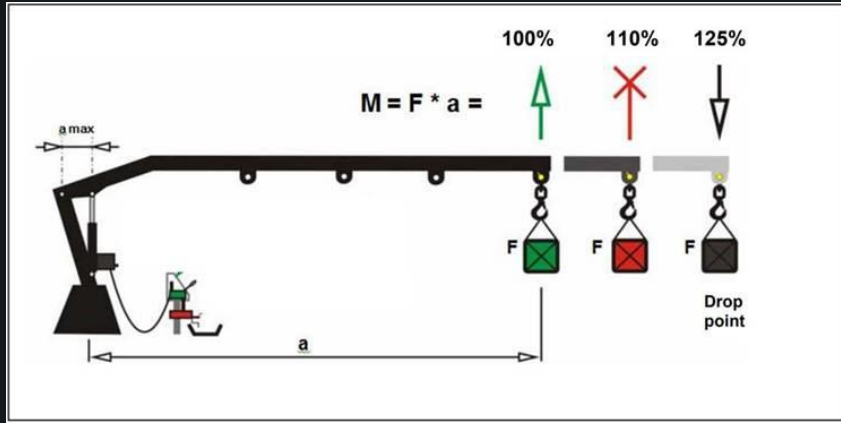
FEDEM simulation takes 75 seconds:



```
-----  
Elapsed time : 0 days 00:01:30.38  
CPU time    : 0 days 00:01:15.06  
-----
```

```
Simulation successfully completed :-)
```


Sensors installed



CRANE PLC/Cloud based solutions

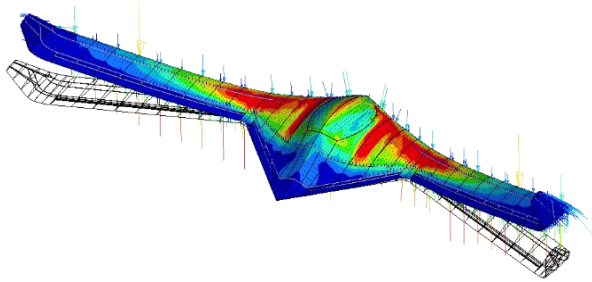




Questions?



ISO 10303 (STEP)



KYKLOS 4.0



1 2

The Mountain Bike experiment

3 4

Digital Twin Based Crane Monitoring

